Fisher[™] 1078 Declutchable Manual Actuator

Fisher 1078 manual actuators are declutchable actuators for manual operation of control valves and equipment that use power actuators. The 1078 manual actuator mounts directly to Fisher 1052 size 70; 1061 sizes 30, 40, 60, 68, 80, and 100; and to all sizes of 2052 actuators.

Features

- Direct Attachment to the Power Actuator Direct mounting to the actuator housing simplifies installation and eliminates the need for yokes and other brackets.
- Engage Manual Actuator At Any Point of Rotation A lever-operated eccentric bearing support on the input shaft allows engagement of the worm gear with the sector at any point of rotation. Because the travel indicator components are mounted on a through shaft, accurate travel indication is maintained during manual actuator disengagement or engagement.
- Positive Operation The disengagement lever is locked in both the engaged and disengaged positions by a detent mechanism, which must be released before the lever can be moved. This provision reduces the possibility of inadvertent or accidental operation. In addition, stop-pins at the fully engaged and fully disengaged positions provide positive limits for lever travel. (Note that stop pins are not available on 1078 size II-FA actuators.)



FISHER 1078 DECLUTCHABLE MANUAL ACTUATOR MOUNTED ON A 2052 SIZE 1 ACTUATOR



FISHER 1078 DECLUTCHABLE MANUAL ACTUATOR MOUNTED ON A 2052 SIZE 1 ACTUATOR AND V300 VALVE WITH FIELDVUE™ DVC6200 DIGITAL VALVE CONTROLLER





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Table 1. Specifications

Available Configurations

Direct and reverse acting; see Handwheel Rotation and the Ordering Information section. (Standard construction is with the handwheel shaft pointing down away from the power actuator as shown in the figure on page 1)

This construction is suitable for cold climate regions and compliant to GOST 15150. However, when ambient temperature is below -50°C (-58°F), it is not advised to operate the handwheel

Manual Actuator Sizes

See tables 1, 2, and 3 See figures 1 and 2 for dimensions

Coupling Shaft Diameters

See tables 1, 2, and 3

Power Actuator Compatibility

See tables 1, 2, and 3

Maximum Torque Output

See tables 1, 2, and 3

Wheel-Rim Force

See tables 1, 2, and 3

Handwheel Rotation

Clockwise handwheel rotation closes the valve. Direct-acting units produce output rotation matching input rotation; reverse-acting units produce output rotation opposite input rotation

Construction Materials

Housing and Cover: Cast iron Drive Sleeve/Gear (Sector): Aluminum/bronze Worm Gear: Heat-treated steel Input Shaft and Eccentric: Low-carbon steel Pin Detent: 300 Series stainless steel Handwheel or Input Shaft Bearings: Bronze

Standard Mounting Positions

 ■ 1052 (size 70)⁽¹⁾: Handwheel down (std) or handwheel right-hand or left-hand mount (optional)
 ■ 1061 (sizes 30, 40, 60, 68, 80, and 100)⁽¹⁾: Handwheel down (std) or handwheel right-hand or left-hand mount (optional)
 ■ 2052 (sizes 1, 2, and 3)⁽¹⁾: Handwheel down (standard) or handwheel right-hand or left-hand mount (optional)

Approximate Weight Without Handwheel

Size AAA: 2.7 kg (6 lbs) Size AA: 6.8 kg (15 lbs) Size A: 9.5 kg (21 lbs) Size 2A: 13.6 kg (30 lbs) Size 1A: 15.9 kg (35 lbs) Size B: 23.1 kg (51 lbs) Size C: 29.9 kg (66 lbs) Size D: 63.5 kg (140 lbs) Size II-FA: 81.6 kg (180 lbs)

Handwheel Weight

6-inch: 1.8 kg (4 lbs) 8-inch: 2.3 kg (5 lbs) 12-inch: 3.2 kg (7 lbs) 16-inch: 6.8 kg (15 lbs) 24-inch: 5.4 kg (12 lbs) 30-inch: 6.4 kg (14 lbs) 36-inch: 7.3 kg (16 lbs)

1. If a positioner is used, the right-hand or left-hand mounting option will be limited to the side away from the positioner.

MANUAL	SHA			POWER STANDARD ACTUATOR HANDWHEEL			MAXI			HANDWHEEL TURNS FOR ROTATION				
SIZE			ACTO	ATOK	DIAMETER		QUL	For Maximum Torque		For Less Than Maximum Torque		Degr	ees	
	mm	Inch	Туре	Size	mm	Inch	N•m	Lbf•in	N	Pounds	N	Pounds	60	90
	12.7	1/2					131	1156	144	32	Divide N•m	Divide lbf•in req'd by 36	4	
AAA (2400 in • lbs)	14.2x15.9 15.9	9/16x5/8 5/8	2052	1	203	8	211	1866	232	52	req'd by 0.91			6
	19.1	3/4					271	2400	298	67	0.51			
	14.3x15.9 15.9	9/16x5/8 5/8	2052		406	16	489	4326	204	45	Divide N∙m req'd by 2.4	Divide lbf∙in req'd by 96	5.3	
	19.1	3/4		2			590	5221	246	54				8
A (8000 in • lbs)	22.2 25.4	7/8 1					818	7241	341	75				
	28.6x31.8 31.8	1-1/8x1-1/4 1-1/4					904	8000	377	83				
	19.1	3/4					1338	11842	279	61				
	22.2 25.4	7/8 1	2052		610	24	1566	13862	326	71			9	
(18000 in • lbs)	28.6x31.8 31.8 38.1 39.7x44.5 44.5 50.8	1-1/8x1-1/4 1-1/4 1-1/2 1-9/16x1-3/4 1-3/4 2		3			2034	18000	424	93		Divide lbf•in req'd by 194		13.5

Table 1. Fisher 2052 Actuator Size Selection and Specifications for Sizes AAA, A, and C

Table 2. Fisher 1052 Actuator Size Selection and Specifications for Sizes 1A, B, and C

MANUAL ACTUATOR SIZE SHAFT SIZI		SIZE	POWER ACTUATOR ⁽¹⁾		STANDARD HANDWHEEL		MAXIMUM TORQUE ⁽²⁾		WHEEL-RIM-FORCE				HANDWHEEL TURNS FOR ROTATION	
SIZE (max output torque)				ACTUATOR(1)		DIAMETER				laximum orque	For Less Than Maximum Torque		Degrees	
torquey	mm	Inch	Туре	Size	mm	Inch	N•m	Lbf•in	Ν	Pounds	N	Pounds	60	90
	31.8, 28.6x 31/8	1-1/4, 1-1/8x 1-1/4												
1A 38.1 1A 31.8x (8200 in.lbs) 38.1 (44.4, 50.8),	1-1/2, 1-1/4x	1052	70(3)	610	24	929	8200	378	85	Divide N•m	Divide lbf∙in	5.3	8	
	(44.4,	1-1/2 (1-3/4, 2), 1-9/16									req'd by 2.4	req'd by 96		
	x44.5	x1-3/4												
P	31.8	3/4 7/8-1 1-1/4	1052	70	610	24	1356	12.000	369	83	Divide N•m	Divide lbf∙in	67	10
B (12,000 in.lbs)	38.1, (44.4, 50.8)	1-1/2, (1-3/4, 2)	1052	70	010	24	1320	12,000	309	83	req'd by 3.6	req'd by 144	6.7	10
							1735	15,355	361	79				
C	31.8	1-1/4					1839	16,275	383	84	Divido Nem	Divide lbf•in		
(18,000 in.lbs)			1052	70	610	24	2034	18,000	414	93		reg'd by 194	9	13.5
1. Field convers	(44.4, 50.8)	(1-3/4, 2)					2034	18,000	414	93		iequ by 194		

Field conversion of actuators for F and G mounting adaptations requires installation of new parts.
 Compare table value with torque requirements of the valve plus the torque required to compress the power actuator spring (from Fisher <u>Catalog 14</u>). Note that dynamic torque of the valve may have a positive or negative effect on total torque required.
 If mounted on the 1052 size 70, the travel is for only 60 Degrees.

MANUAL ACTUATOR SIZE	SHAFT SIZE		POWER ACTUATOR		STANDARD HANDWHEEL DIAMETER		MAXIMUM TORQUE ⁽¹⁾		WHEEL-RIM-FORCE				HANDWHEEL TURNS FOR ROTATION	
(max output									For Maximum Torque		For Less Than Maximum Torque		Degrees	
torque)	mm	Inch	Туре	Size	mm	Inch	N•m	Lbf•in	N	Pounds	N	Pounds	60	90
	12.7 15.9, 14.3x 9.5	1/2 5/8, 9/16x 5/8			152	6	58 138	515 1225	89 214	20 48	Divide N∙m req'd by 0.66	Divide Ibf•in req'd by 26		
2A (4800 in.lbs)	19.1	3/4 ⁽³⁾	1061	30	203	8	239	2120	276	62	Divide N∙m req'd by 0.86	Divide Ibf•in req'd by 34	5.7	8.5
	(22.2, 25.4) 31.8	(7/8,1)			305	12	467 ⁽⁴⁾ 541	4140 ⁽⁴⁾ 4800	360 416	81 94	Divide N∙m req'd by 1.3	Divide Ibf•in req'd by 51		
	19.1	3/4	1061	10			239	2120	276	62	-	-		
	(22.2, 25.4)	(7/8,1)	1061	40, 60, 68	305	12	467	4140	382	86	Divide N•m req'd by 1.2	Divide Ibf∙in req'd by 48	5.3	8
1A (8200 in.lbs)	31.8, 28.6x 31/8 38.1 31.8x 38.1 (44.4, 50.8), 39.7 x44.5	1-1/4, 1-1/8x 1-1/4 1-1/2, 1-1/4x 1-1/2 (1-3/4, 2), 1-9/16 x1-3/4	1061	40, 60, 68	610	24	929	8200	378	85	Divide N•m req'd by 2.4	Divide Ibf∙in req'd by 96	5.3	8
	19.1	3/4					239	2120	66	15				
B	22.2, 25.4	7/8,1	1061	40,	61.0	~ /	468	4140	130	29	Divide	Divide Ibf∙in req'd by 144	6.7	10
(12,000 in.lbs)	31.8 38.1, (44.4, 50.8)	1-1/4 1-1/2, (1-3/4, 2)	1061	60, 68	610	24	1109 1356	9815 12,000	308 377	68 83	N•m req'd by 3.6			10
С	31.8	1-1/4		40,			1109	9815	231	51	Divide	Divide		
(18,000 in.lbs)	(44.4, 50.8)	(1-3/4, 2)	1061	60, 68	610	24	2034	18,000	424	93	N•m req'd by 4.8	lbf∙in req'd by 194	9	13.5
	(44.4, 50.8)	(1-3/4, 2)			762	30	2658	23,524	369	82	Divide N•m req'd by 7.2	Divide Ibf•in req'd by 287		
D (30,000 in.lbs)	54, 63.5 57.2x 63.5	2-1/8, 2-1/2, 2-1/4x 2-1/2	1061	80, 100	914	36	3390	30,000	394	87	Divide	Divide	10.7	16
	76x 63.5, 101.6x 63.5	3x2 1/2,4x 2 1/2	1061		514	0	0550	50,000	534	07	N•m req'd by 8.6	lbf•in req'd by 345		
II-FA ⁽²⁾ (60,000 in.lbs)	76x 63.5, 101.6x 63.5	3x2 1/2,4x 2 1/2	1061	80, 100	406	16	6301	55,762	400	90	Divide N∙m req'd by 15.7	Divide Ibf∙in req'd by 619	48	72

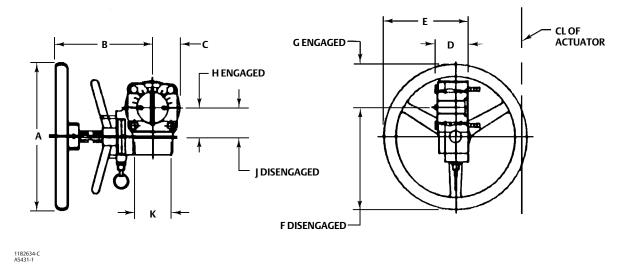
Table 3. Fisher 1061 Actuator Size Selection and Specifications for Sizes 2A, 1A, B, C, D, and II-FA

A S/4 inclusion will also mount on the 1001 size 40, 60, and 68.
 Maximum torque of connection between power and manual actuator.

1078 Size	A	В	с	D	E	F	G	н	J	Square Bolt Pattern	Circular Bolt Pattern	
	mm											
AAA	305	184	40	67	178	204	106	46	51	57.1 SQ		
AA	305	203	56	70	181	216	94	59	64	76.2 SQ		
A	610	381	68	83	337	378	238	67	73	88.9 SQ		
	Inches											
AAA	12.00	7.25	1.56	2.62	7.00	8.02	4.18	1.82	2.02	2.25 SQ		
AA	12.00	8.00	2.19	2.75	7.12	8.50	3.69	2.31	2.50	3.00 SQ		
А	24.00	15.00	2.69	3.25	13.25	14.88	9.38	2.63	2.88	3.50 SQ		

Table 4. Dimensions for Actuator Sizes AAA, AA, and A

Figure 1. Dimensions for Actuator Sizes AAA, AA, and A (also see table 4)



Note: This drawing is a typical view only. For some valves, the handwheel is on the opposite side.

1078 Size	А	В	С	D	E	F	G	Н	J			
	mm											
	152				155	140	17.5					
2A	203	230	55.4	116	181	165	42.9	58.7	63.5			
	305				232	216	93.7					
1.4	305	229	68.3	124	235	229	82.6	69.9	76.2			
1A	610	229	08.5	124	387	381	235	09.9	70.2			
	203				194	191	19.1					
В	305	229	84.1	140	244	241	69.9	82.6	88.9			
	610				397	394	222					
С	610	254	102	149	400	416	200	105	111			
5	762	10.5	117	202	505	506	262	110	105			
D	914	406	117	203	581	583	338	119	125			
II-FA	406	356	117	203	337	328	84	119	125			
	Inches											
	6.00				6.12	5.5	0.69					
2A	8.00	8.00	2.18	4.56	7.12	6.5	1.69	2.31	2.50			
	12.00				9.12	8.5	3.69					
1.4	12.00	0.00	2.60	4.00	9.25	9.00	3.25	2.75	2.00			
1A	24.00	9.00	2.69	4.88	15.25	15.00	9.25	2.75	3.00			
	8.00				7.62	7.50	0.75					
В	12.00	9.00	3.31	5.50	9.62	9.50	2.75	3.25	3.50			
	24.00				15.62	15.50	8.75					
C	24.00	10.00	4.00	5.88	15.75	16.38	7.88	4.12	4.38			
5	30.00	16.00	4.62	0.00	20.25	19.94	10.31	1.60	4.0.4			
D	36.00	16.00	4.62	8.00	23.25	22.94	13.31	4.69	4.94			
II-FA	16.00	14.00	4.62	8.00	13.25	12.94	3.31	4.69	4.94			

Table 5. Dimensions for Actuator Sizes 2A, 1A, B, C, D, and II-FA

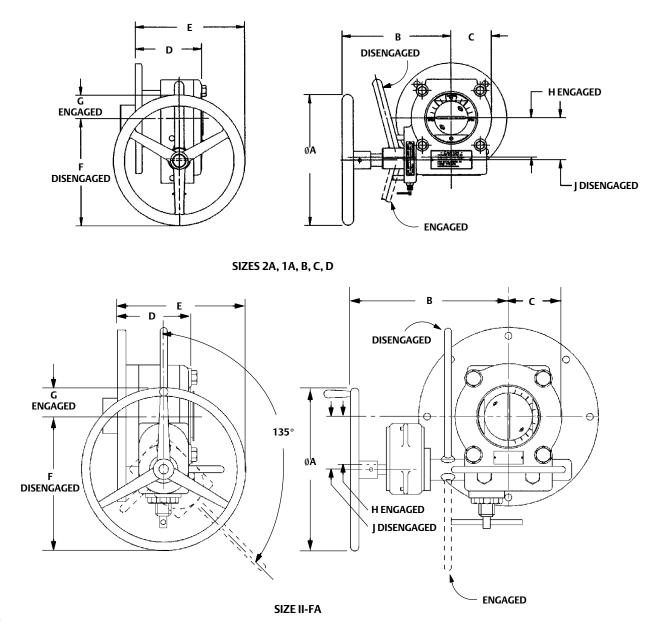


Figure 2. Dimensions for Actuator Sizes 2A, 1A, B, C, D, and II-FA (also see table 5)

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Ordering Information

Whenever a power actuator is ordered with a 1078 manual actuator, all components are configured and mounted according to specifications of the order.

Size AAA, AA, and A

Field installation of the 1078 onto existing actuators with F or G mounting adaptations requires installation of new power actuator parts. (The F and G mounting adaptations are the mounting methods normally used to mount 1052 and 2052 (size 1 and 2) actuators on Fisher valves.) Installation of a valve to bypass cylinder or diaphragm pressure during manual operation is also recommended.

Size 2A, 1A, B, C, D, and II-FA

Field installation of the 1078 onto the following existing actuators with F or G mounting adaptations [1052 (size 70), 2052 (size 3), and 1061 (sizes 30, 40, 60, 68, 80, and 100)] requires additional parts in most cases. Remove the cover and hub and then replace with the 1078 actuator. Most assemblies require a new lever and splined adaptor.

	107	8 ACTUATOR ACT	ION							
VALVE	Actuator Mounting									
	Right-Hand	Left-Hand	Left-Hand (Optional) ⁽³⁾							
8510, 8532, 8580, 8590, and 9500	Direct Acting ⁽¹⁾	Direct Acting	NA							
V150, V200, and V300	Reverse Acting ⁽²⁾	Reverse Acting	Direct Acting							
V250	Reverse Acting	Direct Acting	NA							
V500 and CV500	Reverse Acting	Reverse Acting	NA							
 Direct acting is when the clockwise handwheel rotation produces clockwise valve shaft rotation to close the valve. Reverse acting is when the clockwise handwheel rotation produces counter clockwise valve shaft rotation to close the valve. A left hand ball will be required for the NPS 3 through 12 series B and the NPS 14 through 20, with or without an attenuator. 										

Table 6. Handwheel/Valve Shaft Rotation

When ordering, specify:

1. Power actuator type and size, and valve shaft size.

2. Right or left hand mounting and desired mounting position.

3. Direct or reverse acting manual actuator construction. Refer to the mounting positions shown in the appropriate actuator bulletin and order according to the guidelines in table 6.

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